

$\pm 1^{\circ}\text{C}$, 3 Channel (2-Remote and 1-Local), High Accuracy Temperature Sensor

1 Features

- Temperature range: $-55^{\circ}\text{C} \sim +150^{\circ}\text{C}$
- Temperature accuracy: ($-40^{\circ}\text{C} \sim +125^{\circ}\text{C}$)
 - Local Channel: $\pm 1^{\circ}\text{C}$
 - Remote Channel: $\pm 1^{\circ}\text{C}$
- High resolution: $0.0625^{\circ}\text{C} / 16\text{bits}$
- Conversion time per channel: 16ms
- Digital output:
 - SMBus, I²C interface compatibility
- Supply voltage range: 2.7V ~ 5.5V
- Low quiescent current: (3.3V, 27°C)
- Average current: $16\mu\text{A}$ (0.0625Hz) / $45\mu\text{A}$ (1Hz) / $90\mu\text{A}$ (4Hz)
 - Local Channel: $180\mu\text{A}$
 - Remote Channel: $380\mu\text{A}$
 - Shutdown current: $0.4\mu\text{A}$
- Series Resistance Cancellation, Automatic Beta Compensation, η -Factor Correction

2 Applications

- MCU, GPU, FPGA, DSP, CPU
- Servers, Desktops, and Notebooks
- Industrial and Medical Equipment

3 Description

GD30TS302T is a high-precision, low-power digital temperature sensor compatible with SMBus and I²C interfaces. Up to two remote diode-connected temperature zones can be monitored simultaneously in addition to the local temperature.

GD30TS302T features series resistance cancellation, pro-programmable η factor correction, β value detection and automatic compensation, and programmable temperature thresholds, providing a reliable temperature monitoring solution with high accuracy and low power consumption.

GD30TS302T is especially suitable for temperature measurement using remote transistors (NPN / PNP Type) in servers and processors integrated in advanced processes. GD30TS302T supports automatic compensation of transistor-connected PNP ($0.09 < \beta < 21.36$) to achieve high-precision temperature measurement.

The typical accuracy of GD30TS302T's local and remote channel is $\pm 1^{\circ}\text{C}$. GD30TS302T provide a measurement resolution of 0.0625°C and a measurement range of $-55^{\circ}\text{C} \sim 150^{\circ}\text{C}$. GD30TS302T are available in $3.0\text{mm} \times 3.0\text{mm}$, 10 pin MSOP and $3\text{mm} \times 3\text{mm}$, 10 pin DFN packages

Device Information¹

| PART NUMBER | PACKAGE | BODY SIZE (NOM) |
|-------------|---------|--------------------------------------|
| GD30TS302T | MSOP-10 | $3.00\text{mm} \times 3.00\text{mm}$ |
| | DFN-10 | $3.00\text{mm} \times 3.00\text{mm}$ |

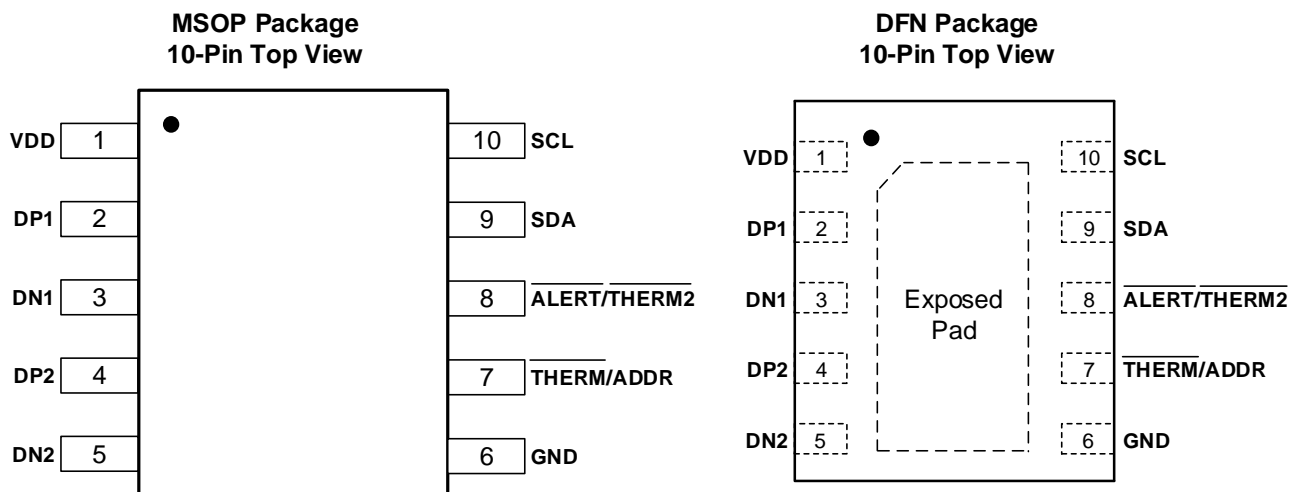
1. For packaging details, see [Package Information](#) section.

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4 Device Overview

4.1 Pinout and Pin Assignment



4.2 Pin Description

| PINS | | PIN TYPE ¹ | FUNCTION |
|----------------|-----|-----------------------|---|
| NAME | NUM | | |
| VDD | 1 | P | Positive supply voltage, 2.7 V to 5.5 V. |
| DP1 | 2 | AI | Positive connection of first Remote Channel. |
| DN1 | 3 | AI | Negative connection of first Remote Channel. |
| DP2 | 4 | AI | Positive connection of second Remote Channel. |
| DN2 | 5 | AI | Negative connection of second Remote Channel. |
| GND | 6 | G | Supply ground connection. |
| THERM/ ADDR | 7 | DI/DO | 1) Thermal shutdown pin; Open-drain, requires pullup resistor to VDD. 2) Address select pin. |
| ALERT / THERM2 | 8 | DO | Thermal shutdown pin; Open-drain, requires pullup resistor to VDD. |
| SDA | 9 | DI/DO | Serial data line for SMBus. Open-drain, requires pullup resistor to VDD. |
| SCL | 10 | DI | Serial clock line for SMBus. Open-drain, requires pullup resistor to VDD. |

1. P = power, G = Ground, DI = Digital input, AI = Analog input, DO = Digital Output, IO=input and output.

5 Parameter Information

5.1 Absolute Maximum Ratings

Exceeding the operating temperature range (unless otherwise noted)¹

| SYMBOL | PARAMETER | MIN | MAX | UNIT |
|------------------|--|------|-----------------------|------|
| V _{DD} | Power Supply Voltage VDD | -0.3 | 6 | V |
| | DP1/DP2 Pin Input Voltage | -0.3 | V _{DD} + 0.3 | V |
| | DN1/DN2 Pin Input Voltage | -0.3 | 0.3 | V |
| | $\overline{\text{THERM}}$ / ADDR , $\overline{\text{ALERT}}$ / $\overline{\text{THERM2}}$, SCL, SDA Pin Voltage | -0.3 | 6 | V |
| I _{in} | Input current | | 10 | mA |
| T _J | Junction Temperature | | 150 | °C |
| T _A | Operating Range | -55 | 150 | °C |
| T _{stg} | Storage temperature | -60 | 160 | °C |

1. Unless otherwise specified, the specifications in the above table apply within the atmospheric temperature range. Stresses beyond the range may cause permanent damage to the device.

5.2 Recommended Operation Conditions

| SYMBOL ¹ | PARAMETER | MIN | TYP | MAX | UNIT |
|---------------------|-----------------------|-----|-----|-----|------|
| V _{DD} | Power Supply Voltage | 2.7 | 3.3 | 5.5 | V |
| T _A | Operating Temperature | -50 | | 150 | °C |

1. Unless otherwise specified, the specifications in the above table apply within the atmospheric temperature range.

5.3 Electrical Sensitivity

| SYMBOL ¹ | CONDITIONS | VALUE | UNIT |
|-----------------------|---|-------|------|
| V _{ESD(HBM)} | Human-body mode (HBM), per ANSI/ESDA/JEDEC JS-001-2017 | ±8000 | V |
| V _{ESD(MM)} | Charged-device model (CDM), per ANSI/ESDA/JEDEC JS-002-2022 | ±1000 | V |
| LU | Latch-Up, per JESD 78, Class IA | ±200 | mA |

1. Unless otherwise noted, the specifications in the above table apply within the atmospheric temperature range.

5.4 Electrical Characteristics

Unless otherwise specified, the following data are the characteristics of the chip at $T_A = -40^{\circ}\text{C} \sim 125^{\circ}\text{C}$ and $V_{DD} = 2.7\text{V} \sim 5.5\text{V}$; where TYP condition is $T_A = 27^{\circ}\text{C}$ and $V_{DD} = 3.3\text{V}$.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|--|------------------------------|--|--------------------|--------------------|-------------|-----------------------------|
| TEMPERATURE MEASUREMENT | | | | | | |
| T_{Local} | Local Temperature Channel | $T_L = -5^{\circ}\text{C} \text{ to } +100^{\circ}\text{C}$ | | ± 0.5 | ± 1 | $^{\circ}\text{C}$ |
| | Accuracy | $T_L = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$ | | ± 0.5 | ± 1.5 | |
| T_{Remote} | Remote Temperature Channel | $T_L/T_R = -5^{\circ}\text{C} \text{ to } +100^{\circ}\text{C}$ | | ± 0.5 | ± 1 | $^{\circ}\text{C}$ |
| | Accuracy | $T_L/T_R = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}$ | | ± 0.5 | ± 1.5 | |
| PSRR | PSRR of local channel | $V_{DD} = 2.7 \sim 5.5\text{V}$ | | ± 0.0625 | ± 0.125 | $^{\circ}\text{C}/\text{V}$ |
| | PSRR of remote channel | $V_{DD} = 2.7 \sim 5.5\text{V}$ | | ± 0.0625 | ± 0.125 | |
| | Resolution | All Channel | | 0.0625 | | $^{\circ}\text{C}$ |
| | Conversion Time | Local channel | | 16 | 17.5 | ms |
| | | Remote channel1 / 2 | | 16 | 17.5 | |
| | Remote sensor source current | High | | 120 | | μA |
| | | Medium | | 45 | | |
| | | Low | | 7.5 | | |
| | η of remote transistor | | | 1.008 | | |
| SERIAL INTERFACE | | | | | | |
| | High-level input voltage | | $0.7 \cdot V_{DD}$ | | | V |
| | Low-level input voltage | | | $0.3 \cdot V_{DD}$ | | V |
| | Hysteresis | | | 0.22 | | V |
| | SDA output-low sink current | | 6 | | | mA |
| | Low-level output voltage | $I_O = 6\text{mA}$ | | 0.15 | 0.4 | V |
| | Input capacitance | | | 3 | | pF |
| | Serial bus timeout | | | 30 | | ms |
| THERM / ADDR、ALERT / THERM2 Pin | | | | | | |
| I_{sink} | Output-low sink current | | 6 | | | mA |
| | Low-level output voltage | $I_O = 6\text{mA}$ | | 0.15 | 0.4 | V |
| POWER SUPPLY | | | | | | |
| V_{DD} | Supply voltage range | | 2.7 | 3.3 | 5.5 | V |
| I_Q | Quiescent current | Average current (0.0625Hz) | | 16 | 30 | μA |
| | | Average current (1Hz) | | 45 | 90 | |
| | | Average current (4Hz, default) | | 90 | 145 | |
| | | Active conversion, local channel | | 180 | 300 | |
| | | Active conversion, remote channel | | 380 | 520 | |
| | | Shutdown Mode | | 0.4 | 4.2 | |

Electrical Characteristics (Continued)

Unless otherwise specified, the following data are the characteristics of the chip at $T_A = -40^{\circ}\text{C} \sim 125^{\circ}\text{C}$ and $V_{DD} = 2.7\text{V} \sim 5.5\text{V}$; where TYP condition is $T_A = 27^{\circ}\text{C}$ and $V_{DD} = 3.3\text{V}$.

| SYMBOL | PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|--------------------------|------------|-----|-----|-----|------|
| POWER SUPPLY | | | | | | |
| | Power-on-reset threshold | | | 1.6 | 2.3 | V |

5.5 Typical Characteristic

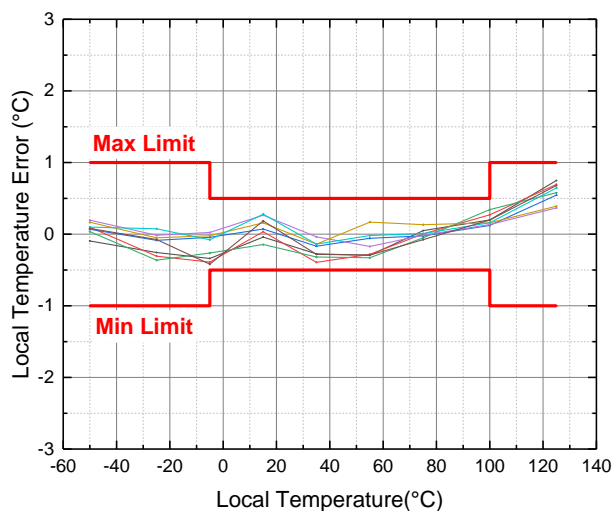


Figure 1. Local Temperature Error vs. Ambient Temperature at $V_{DD}=3.3V$

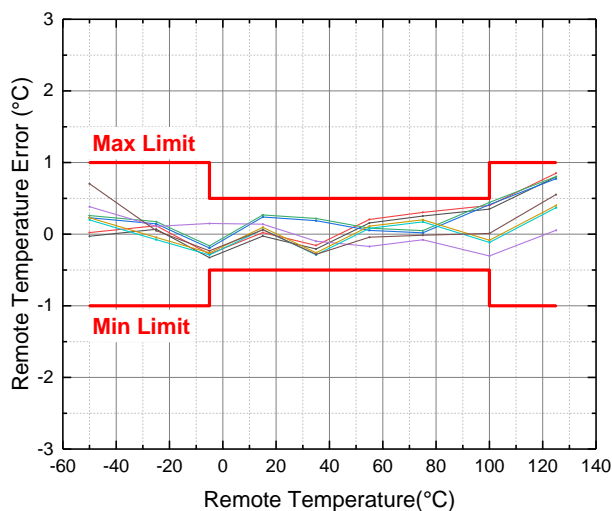


Figure 2. Remote Temperature Error vs. Device Junction Temperature at $V_{DD}=3.3V$

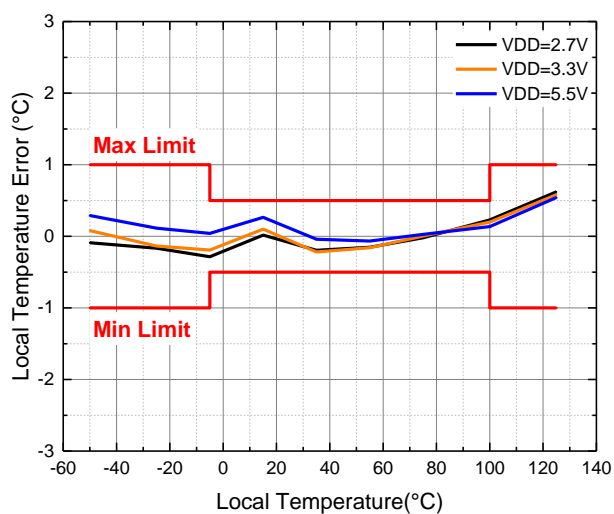


Figure 3. Local Temperature Error Power Supply Sensitivity vs. Ambient Temperature

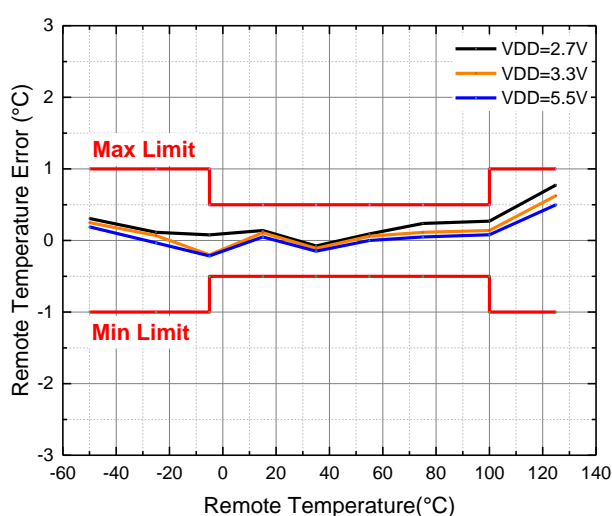


Figure 4. Remote Temperature Error Power Supply Sensitivity vs. Device Junction Temperature

Typical Characteristic (Continued)

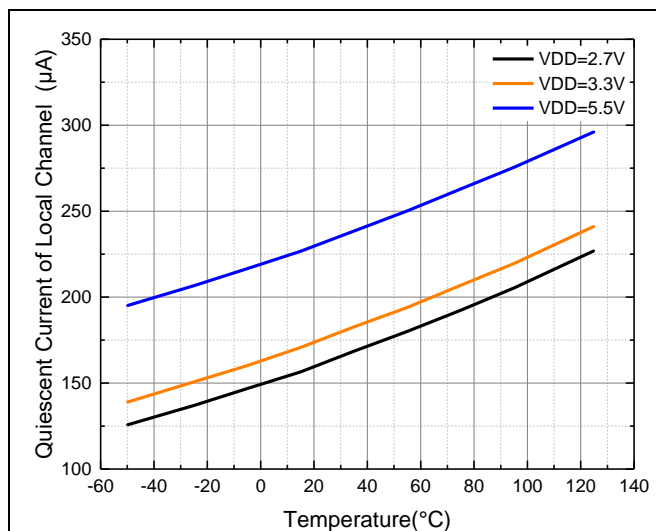


Figure 5. Quiescent Current in Local Channel vs. Ambient Temperature

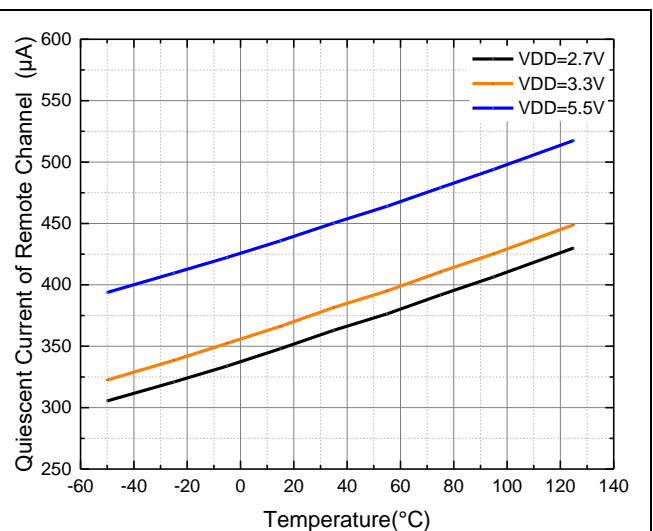


Figure 6. Quiescent Current in Remote Channel vs. Ambient Temperature

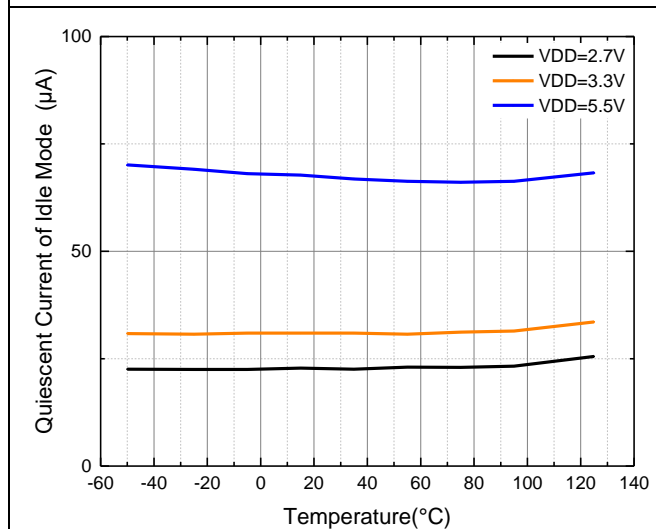


Figure 7. Quiescent Current in IDLE Mode vs. Ambient Temperature

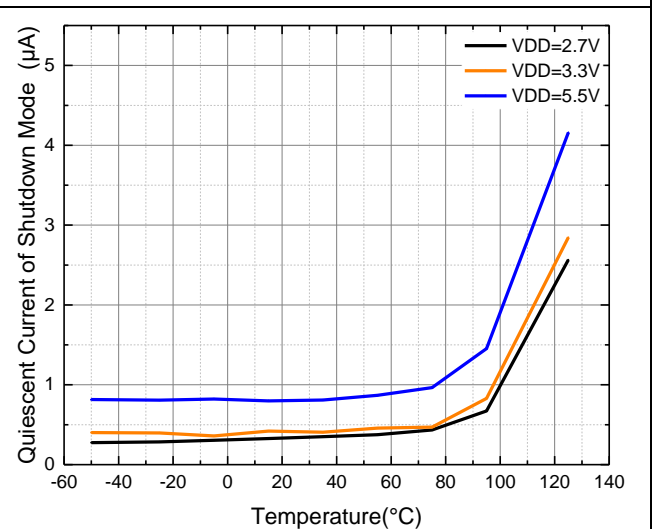
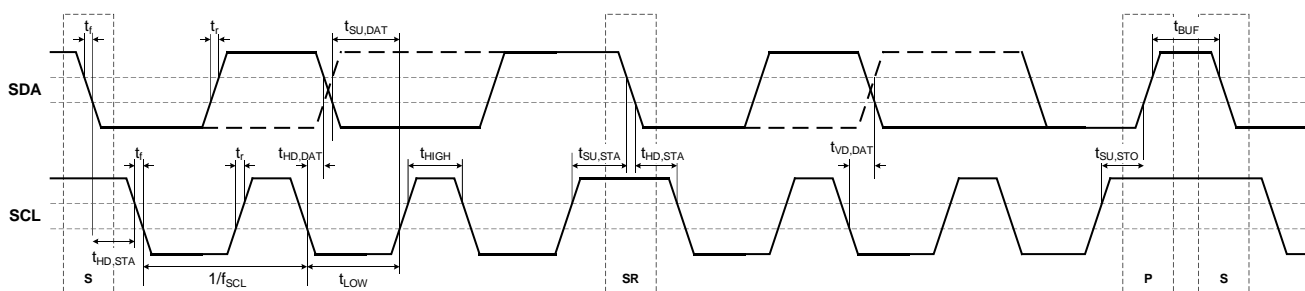


Figure 8. Quiescent Current in Shutdown Mode vs. Ambient Temperature

5.6 I²C Timing Requirements

Unless otherwise specified, the following data are the characteristics of the chip at $T_A = -40^{\circ}\text{C} \sim 125^{\circ}\text{C}$ and $V_{DD} = 2.7\text{V} \sim 5.5\text{V}$.

| SYMBOL | DESCRIPTION | Standard-Mode | | Fast-Mode | | High-Speed Mode | | UNIT |
|---------------------|---|---------------|------|--------------------------------|-----|-----------------|------|---------------|
| | | MIN | MAX | MIN | MAX | MIN | MAX | |
| f_{SCL} | SCL operating frequency | | 100 | | 400 | | 2500 | kHz |
| $t_{\text{HD,STA}}$ | hold time after repeated start condition; After this period, the first clock is generated | 4.0 | | 0.6 | | 0.16 | | μs |
| t_{LOW} | SCL clock low period | 4.7 | | 1.3 | | 0.16 | | μs |
| t_{HIGH} | SCL clock high period | 4.0 | | 0.6 | | 0.06 | | μs |
| $t_{\text{SU,STA}}$ | repeated start condition setup time | 4.7 | | 0.6 | | 0.16 | | μs |
| $t_{\text{HD,DAT}}$ | data hold time | 0 | | 0 | | 0 | 70 | ns |
| $t_{\text{SU,DAT}}$ | data setup time | 250 | | 100 | | 10 | | ns |
| t_r | rise time of SCL | | 1000 | 20 | 300 | 10 | 40 | ns |
| | rise time of SDA | | | | | 10 | 80 | |
| t_f | fall time of SCL | | 300 | $20 \cdot V_{\text{CC}} / 5.5$ | 300 | 10 | 40 | ns |
| | fall time of SDA | | | | | 10 | 80 | |
| $t_{\text{SU,STO}}$ | stop condition setup time | 4.0 | | 0.6 | | 0.16 | | μs |
| t_{BUF} | bus free time between stop and start condition | 4.7 | | 1.3 | | | | μs |
| $t_{\text{VD,DAT}}$ | data valid time | | 3.45 | | 0.9 | | | μs |
| C_b | capacitive load for each bus line | | 400 | | 400 | | 100 | pF |



6 Functional Description

6.1 Chip Function Modes

6.1.1 Connections of Remote Channels

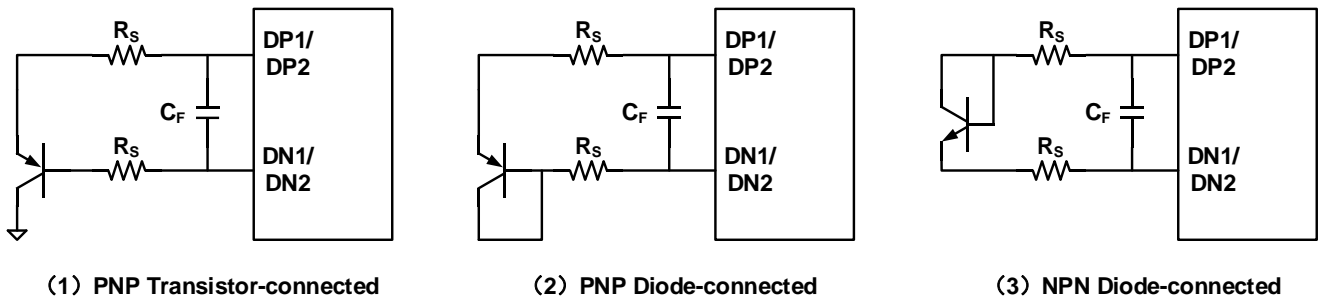


Figure 9. Remote BJT connections diagram

GD30TS302T supports three different remote temperature measurement connection methods: PNP transistor connection, PNP diode connection, and NPN diode connection, as shown in [Figure 9](#).

6.1.2 Continuous Conversion Mode

The default mode of operation of the GD30TS302T is the continuous conversion mode. In this mode, the GD30TS302T will be converted sequentially in the order of local channel, remote 1 channel, and remote 2 channel. The LEN, REN1, and REN2 bit in Configuration Register 2 (41h) control the channels during continuous conversion. If some channels are not activated, they will be skipped. The R3:R0 bit in the Conversion Rate Register (0Ah) allows the GD30TS302T to be configured in conversion rates, as detailed in [Conversion Rate Register](#).

All channels of the GD30TS302T can output 12bits temperature results with a resolution of 0.0625°C, and the results are stored in the Temperature Register of the corresponding channel using two bytes. In the Standard Mode, the temperature measurement range of all channels is 0 ~ 128°C, the results of negative temperature always output 0000h, and the results greater than or equal to 128°C always output 7FFFh.

GD30TS302T offers Extended Mode for a wider range of temperature measurements. Writing the RANGE bit in Configuration Register 1 (03h/09h) to 1 will enter the Extended Mode. GD30TS302T outputs the temperature measurement result in the Extended Mode after the next temperature conversion. In this mode, the final temperature measurement result is the sum of the actual temperature measurement result and 64°C (40h), and the temperature measurement range will be extended to -64 ~ 192°C. [Table 1](#) and [Table 2](#) show the high- and low-byte data formats of the Temperature Registers in Standard and Extended Mode.

The recommended temperature measurement range for all channels in GD30TS302T is -50°C ~ 150°C.

Table 1. Temperature Data Format (Local and Remote Temperature High Bytes)

| Temperature (°C) | Local / Remote Temperature Register High Byte | | | |
|------------------|---|-----|---------------|-----|
| | Standard Mode | | Extended Mode | |
| | BIN | HEX | BIN | HEX |
| -64 | 0000 0000 | 00 | 0000 0000 | 00 |
| -50 | 0000 0000 | 00 | 0000 1110 | 0E |
| -25 | 0000 0000 | 00 | 0010 0111 | 27 |
| 0 | 0000 0000 | 00 | 0100 0000 | 40 |
| 1 | 0000 0001 | 01 | 0100 0001 | 41 |
| 5 | 0000 0101 | 05 | 0100 0101 | 45 |
| 10 | 0000 1010 | 0A | 0100 1010 | 4A |
| 25 | 0001 1001 | 19 | 0101 1001 | 59 |
| 50 | 0011 0010 | 32 | 0111 0010 | 72 |
| 75 | 0100 1011 | 4B | 1000 1011 | 8B |
| 100 | 0110 0100 | 64 | 1010 0100 | A4 |
| 125 | 0111 1101 | 7D | 1011 1101 | BD |
| 127 | 0111 1111 | 7F | 1011 1111 | BF |
| 150 | 0111 1111 | 7F | 1101 0110 | D6 |
| 191 | 0111 1111 | 7F | 1111 1111 | FF |

Table 2. Temperature Data Format (Local and Remote Temperature Low Bytes)

| Temperature (°C) | Local / Remote Temperature Register Low Byte | |
|------------------|--|-----|
| | BIN | HEX |
| 0.0625 | 0001 0000 | 10 |
| 0.125 | 0010 0000 | 20 |
| 0.25 | 0100 0000 | 40 |
| 0.5 | 1000 0000 | 80 |
| 0.75 | 1100 0000 | C0 |
| 0.9375 | 1111 0000 | F0 |

6.1.3 Shutdown Mode

Shutdown mode reduces the power consumption of the chip by shutting down all circuitry except the serial interface, reducing the current of the GD30TS302T to 0.4μA (typical). Writing the SD bit in Configuration Register 1 (03h/09h) to 1 will enter into the shutdown mode. When such configured, the GD30TS302T will abort the current temperature conversion and shut down immediately. Write the SD bit to 0 will exit from shutdown mode and GD30TS302T will re-enter into continuous conversion mode.

In particular, writing the LEN, REN1, and REN2 bits in Configuration Register 2 to 0 at the same time will also enter into shutdown mode. In this case, writing any one or more of above bits as 1 will exit from shutdown mode.

6.1.4 One-Shot Mode

GD30TS302T can be configured in One-Shot mode. When the GD30TS302T is in shutdown mode (SD=1), writing any value to the One-Shot Register (0Fh) enables a single temperature conversion, and the value is not stored in the One-Shot Register. After this single temperature conversion, the GD30TS302T returns to the shutdown mode. When continuous temperature measurement is not required, this function can significantly reduce the power consumption of the chip.

6.1.5 β Detection and Compensation

GD30TS302T can detect the β value of the transistor-connected PNP (as shown in [Figure 9](#)) for remote temperature measurement, and compensate for different β values to avoid the error caused by β values. GD30TS302T provides two β compensation modes: automatic and manual. GD30TS302T enters the automatic β compensation mode by writing the BC3:BC0 bit of the β Compensation Register (25h/26h) to 1XXXb. In this mode, GD30TS302T will automatically detect the β value of the remote PNP before the remote temperature measurement, and automatically adjust the internal compensation circuit for this β value.

GD30TS302T enters the manual β compensation mode by writing the BC3:BC0 bit of the β Compensation Register (25h/26h) to 0000b~0110b. In this mode, GD30TS302T no longer automatically detects the β value of the connected remote PNP, but instead works based on the value written into the β Compensation Register. Therefore, when using the manual β compensation mode, the β value of the remote PNP should be clarified in advance.

The β compensation circuit inside the chip can be manually turned off by writing the BC3:BC0 bit of the β Compensation Register as 0111b. In order to avoid excessive temperature measurement errors, it is necessary to ensure that the β value of the selected remote PNP is greater than 50 at this time.

The above discussion is based on the remote temperature measurement using the transistor-connected PNP. When using a diode-connected PNP/NPN, the chip will always automatically shut down the β compensation circuit, regardless of whether the chip is configured in automatic or manual compensation mode. Therefore, when selecting the diode-connected PNP/NPN, it should be ensured that the β value of the selected remote BJT is greater than 50.

The above configuration of the β Compensation Registers is described in [β Compensation Register](#).

6.1.6 Series Resistance Cancellation and Filtering

When using GD30TS302T for remote temperature measurement, it is necessary to consider the influence of the remote series resistance R_s on the remote temperature measurement results. The parasitic resistance of the traces on the PCB is one of the main sources of R_s . GD30TS302T automatically eliminates the effects of series resistance R_s up to 1kohm.

In addition, ambient noise can also reduce the accuracy of GD30TS302T temperature measurement. A 65kHz low-pass filter is integrated between the DPX and DNX pins of the GD30TS302T to suppress temperature measurement errors caused by the above-mentioned environmental noise. Nonetheless, it is recommended to connect a filter resistor R_s in series on the DPX and DNX pins of the GD30TS302T and a filter capacitor C_f across the two pins to form an off-chip low-pass filter that allows the chip to better filter out extraneous coupled signals

between these pins, as shown in [Figure 15](#).

The sum of the above filter resistors and PCB trace resistors should be less than 1k Ω ; the above filter capacitor C_F should be $\leq 1\text{nF}$. The recommended filter resistor and capacitor are $R_S=50\Omega$, $C_F=100\text{pF}$. In some specific applications, the filter resistor and capacitor should be adjusted appropriately for better remote temperature measurement accuracy.

In addition, the GD30TS302T integrates a two-level programmable digital filter, which can be selected by configuring the Filter Control register (40h), as detailed in [Filter Control Register](#). When Level 1 is selected, the final remote temperature measurement result is the average of the last four temperature measurement results. When Level 2 is selected, the final remote temperature measurement results is the average of the last eight temperature measurement results. A schematic diagram of the filter's operation is shown in [Figure 10](#). The filter is disabled by default after POR.

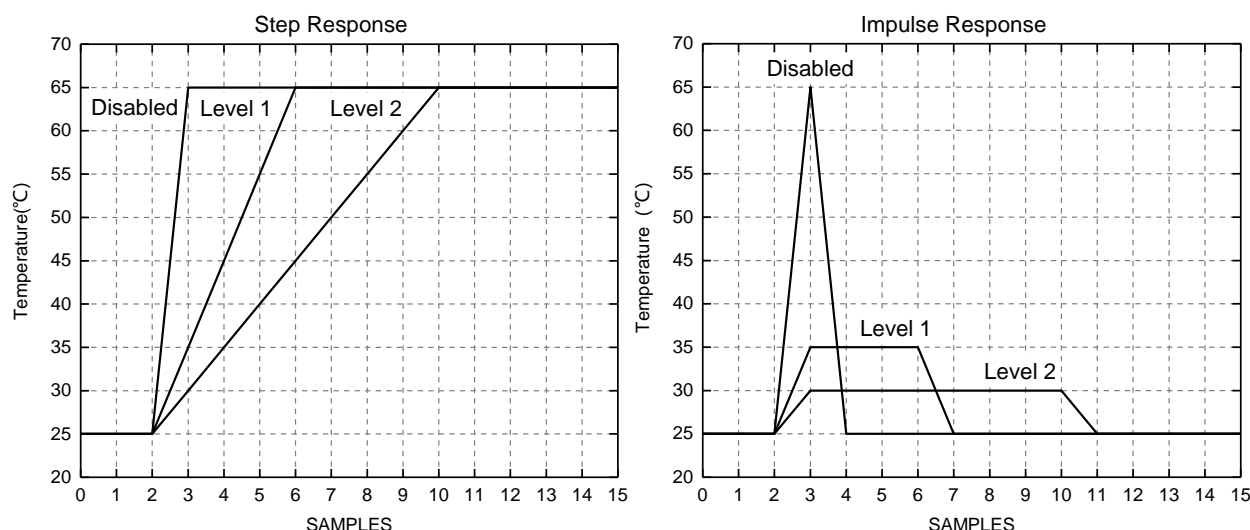


Figure 10. Filter Response to Impulse and Step Inputs

6.1.7 Sensor Fault

The GD30TS302T can sense a fault at the DPX input resulting from incorrect diode connection. When the voltage of the DPX pin is higher than $(V_{DD} - 0.3V)$, the GD30TS302T will judge that the pin is open, the OPEN bit in the Status Register (02h) will be set to 1, and the temperature measurement result of the remote channel will return 0000h. If the chip is in ALERT mode, the ALERT pin will be activated (ALERT = 0).

GD30TS302T can also continuously detect the short circuit misconnection between the DPX pin and the DNX / GND pin. The temperature measurement result for this remote channel will also return 0000h, but the OPEN bit in the Status Register will not be activated. The behavior of the OPEN bit is shown in [Open bit \(POR=0\)](#).

When not using the remote channels of the GD30TS302T, the DPX pin and DNX pin of the corresponding channel must be shorted to prevent meaningless misconnection detection.

6.1.8 Therm and Alert Function

GD30TS302T use $\overline{\text{THERM}}$ and $\overline{\text{ALERT}}/\overline{\text{THERM2}}$ pin to implement the Therm and Alert function.

6.1.8.1 THERM Mode

GD30TS302T compares the high byte of each channel results to the value in the Local/Remote THERM Limit Register (20h/19h/1Ah) after each conversion. If the result is higher than the value of the THERM Limit Register by the number of times defined by CTH2:CTH0 bits in the Consecutive Alert Register (22h), the LTHRM/R1THRM/R2THRM bit in the THERM Status Register (37h) will be set to 1. If any of the above three bits are set to 1, the THERM bit in the Status Register (02h) will be set to 1. If any of the above status bits are activated, the $\overline{\text{THERM}}$ pin will be activated at the same time ($\overline{\text{THERM}} = 0$).

The above status bits will remain active, until the temperature measurement result is below the value of the THERM Limit Register minus the THERM Hysteresis Register (21h) by the number of times defined by CTH2:CTH0 bits in the Consecutive Alert Register (22h), after which the above status bit is reset to 0. The $\overline{\text{THERM}}$ pin will remain active until all of the above status bits are reset to 0, after which the $\overline{\text{THERM}}$ pin will be reset to 1.

6.1.8.2 THERM2 Mode

Writing the AL/TH bit in Configuration Register 1 to 1, and the $\overline{\text{ALERT}}/\overline{\text{THERM2}}$ pin can be configured as a $\overline{\text{THERM2}}$ pin. If the temperature measurement result is higher than the High Limit Register of the channel (0Bh / 0Dh&13h / 15h&17h) by the number of times defined by CTH2:CTH0 bits in the Consecutive Alert Register (22h), the LHIGH/R1HIGH/R2HIGH bit in the High Limit Status Register (35h) will be set to 1. The HIGH bit in the Status Register will be set to 1 if any of the above three bits are set to 1. The $\overline{\text{THERM2}}$ pin will be activated at the same time ($\overline{\text{THERM2}} = 0$).

The above status bits will remain active, until the temperature measurement result is below the value of the High Limit Register minus the THERM Hysteresis Register (21h) by the number of times defined by CTH2:CTH0 bits in the Consecutive Alert Register (22h), after which the above status bit is reset to 0. The $\overline{\text{THERM2}}$ pin will remain active until all of the above status bits are reset to 0, after which the $\overline{\text{THERM2}}$ pin will be reset to 1.

6.1.8.3 ALERT Mode

Writing the AL/TH bit in Configuration Register 1 to 0, and the $\overline{\text{ALERT}}/\overline{\text{THERM2}}$ pin can be configured as a $\overline{\text{ALERT}}$ pin. If the temperature measurement result is higher than the High Limit Register of the channel (0Bh / 0Dh&13h / 15h&17h) or below the Low Limit Register of the channel (0Ch / 0Eh &14h / 16h &18h) by the number of times defined by CTH2:CTH0 bits in the Consecutive Alert Register (22h), the corresponding bits in the High Limit Status Register (35h) or Low Limit Status Register (36h) will be set to 1, and the HIGH bit or LOW bit in the Status Register will also be set to 1, as shown in [HIGH/LOW bit \(POR=0\)](#). The above status bits will remain active until the Status Register (35h&36h) is read when the result is no longer in a overtemperature state, after which the above status bit will be reset to 0. When GD30TS302T successfully responding to an SMBus alert command, the corresponding status bit will also be reset immediately.

The MASK bit in Configuration Register 1 controls the behavior of the $\overline{\text{ALERT}}$ pin only in ALERT Mode. When MASK=0, any of the above status bits are activated, and the $\overline{\text{ALERT}}$ pin will be activated at the same time ($\overline{\text{ALERT}} = 0$). After all the above status bits are reset to 0, the $\overline{\text{ALERT}}$ pin will be reset to 1. When MASK=1, the $\overline{\text{ALERT}}$ pin will be masked and will never be activated, but the above status bit will not be affected by the MASK bit.

Each MASK bit in the Channel Mask Register (1Fh) acts the same as the MASK bit in configuration register 1 to corresponding channel.

The above function is shown in Figure 11.

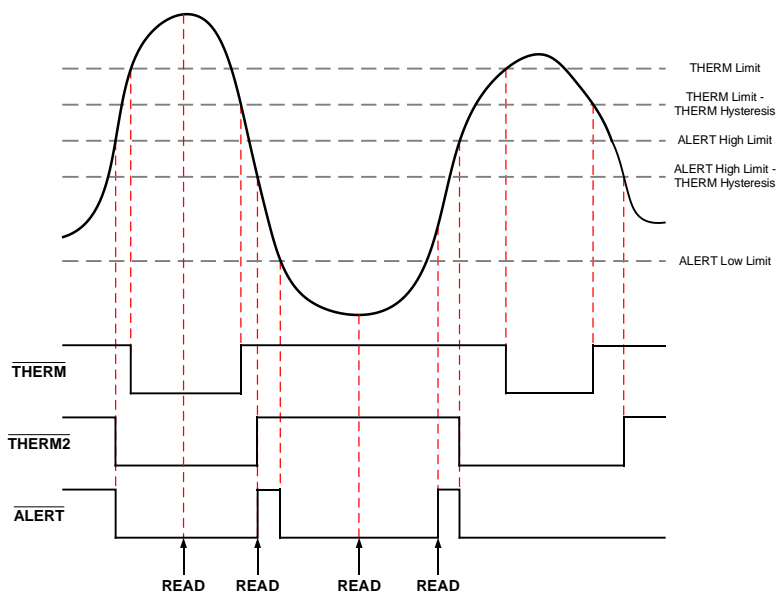


Figure 11. Therm and Alert Function Operation

6.2 Serial Interface

6.2.1 Bus Overview

The GD30TS302T is compatible with SMBus and I²C interfaces. In the SMBus protocol, the device that initiates the transfer is called a master, and the devices controlled by the master are slaves. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates the START and STOP conditions. To address a specific device, a START condition is initiated, indicated by pulling the data line (SDA) from a high- to low-logic level when the SCL pin is high. All slaves on the bus receive the 8-bits slave address on the rising edge of the clock, and the last bit indicates whether a read or write operation is intended. During the ninth clock pulse, the addressed slave generates an acknowledge and pulls the SDA pin low to respond to the master. A data transfer is then initiated and sent over eight clock pulses followed by an acknowledge bit. When all data are transferred, the master generate a STOP signal to end the communication by pulling SDA from low to high when SCL is high.

During the data transfer, the SDA pin must remain stable when the SCL pin is high because any change in the SDA pin when the SCL pin is high is interpreted as a START or STOP signal.

6.2.2 Serial Bus Address

To communicate with GD30TS302T, the master must first address slave devices through an address byte. The address byte has seven address bits and a read-write (R/W) bit that indicates the intent of executing a read or write operation. [Table 3](#) lists the slave addresses of different GD30TS302T series.

Table 3. Slave Address of GD30TS302T series

| GD30TS302T Series | SMBus Address |
|--------------------|--|
| GD30TS302TAMTR-I0A | Determined by the R _P on the $\overline{\text{THERM}}$ / ADDR Pin |
| GD30TS302TAMTR-I0B | 1001 100 |
| GD30TS302TAMTR-I0C | 0011 000 |
| GD30TS302TAETR-I0A | Determined by the R _P on the $\overline{\text{THERM}}$ / ADDR Pin |

The slave address of the GD30TS302TA is determined by the pull-up resistor R_P of the pin, and the correspondence is shown in [Table 4](#). Within 10ms after the GD30TS302TA is powered on, the chip automatically detects the pull-up resistor R_P of the pin and determines the corresponding slave address. During this time (10ms after POR), do not pull the pins low or communicate with the GD30TS302TA. In order to communicate with the GD30TS302TA properly, the error of the R_P in [Table 4](#) should be $\leq \pm 5\%$.

Table 4. Slave Address of GD30TS302TA

| R _P on THERM/ADDR Pin | SMBus Address |
|----------------------------------|---------------|
| 4.7kohm | 1111 100 |
| 6.8kohm | 1011 100 |
| 10kohm | 1001 100 |
| 15kohm | 1101 100 |
| 22kohm | 0011 100 |
| 33kohm | 0111 100 |

6.2.3 Read and Write Operation

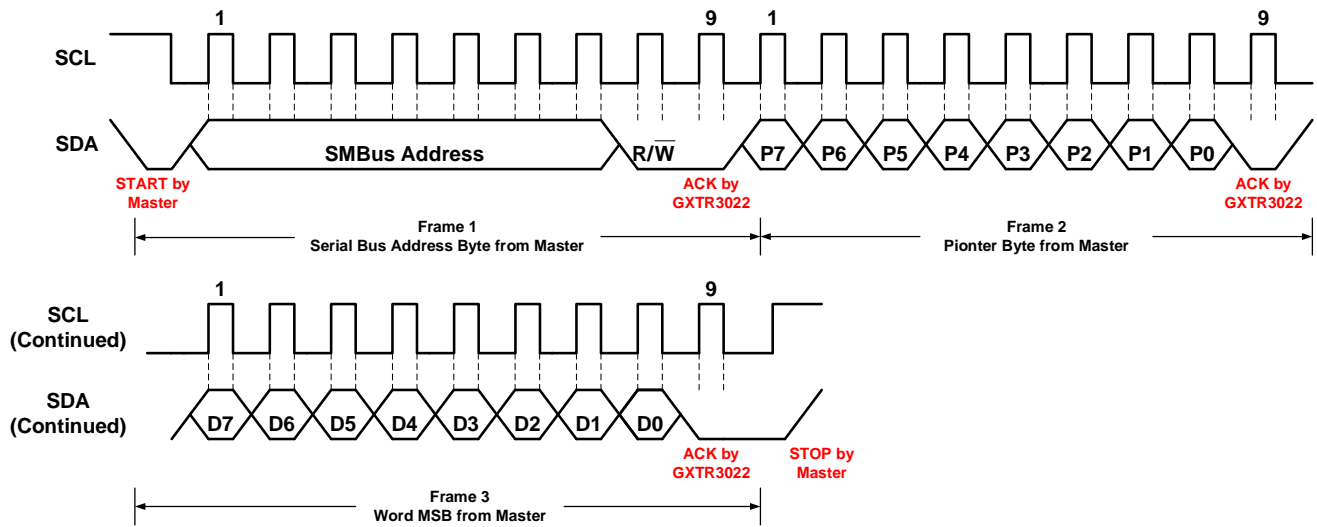


Figure 12. Two-wire Write Timing Diagram for Write Word Format

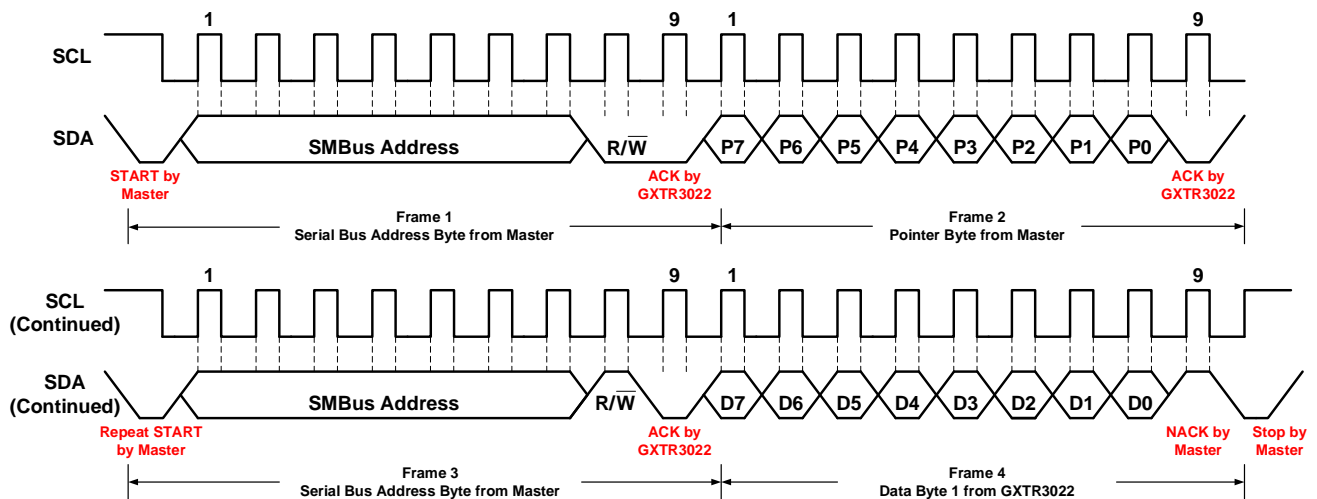


Figure 13. Two-wire Read Timing Diagram for Single-Byte Read Format

GD30TS302T allows the host to access specific internal registers by writing the target value to a pointer register. When writing data to GD30TS302T, after sending a slave address byte with a low R/W bit, the corresponding pointer register byte is sent to write the data to a specific register in the GD30TS302T. Each writing to the GD30TS302T needs a pointer register byte.

When reading data from GD30TS302T, the slave address byte with the R/W bit is low is first sent, and then the corresponding pointer register byte is sent. The master then generates a Start signal again and sends the slave address byte with the high R/W bit to initiate the read command. There is no need to repeatedly send the pointer byte if reading data from the same register. GD30TS302T allow the host to automatically read data from the register specified by the previous pointer byte. When reading data is complete, the host needs to send a NACK bit at the end of the last byte to end the read operation. [Figure 12](#) and [Figure 13](#) show the read and write operations.

6.2.4 SMBus Alarm Function

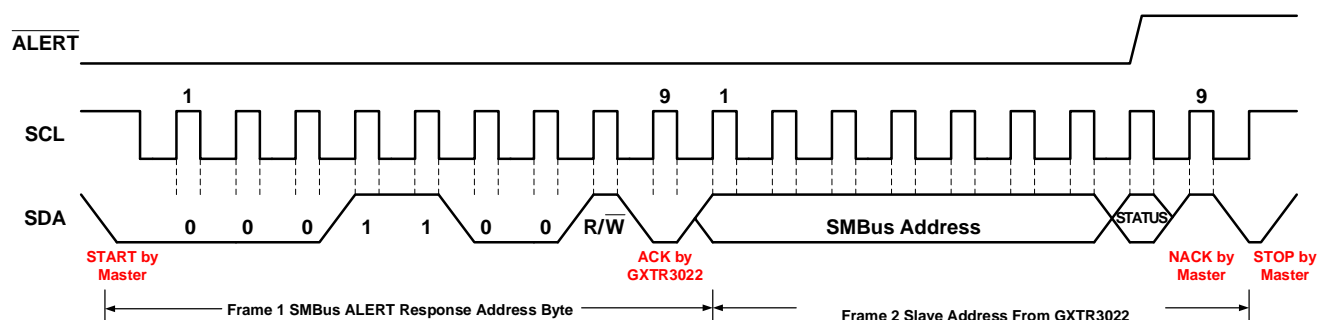


Figure 14. Timing Diagram for SMBus ALERT

GD30TS302T supports SMBus Alert function. When the GD30TS302T is in ALERT mode, the host can send the SMBus Alert command (19h) to the bus. If the $\overline{\text{ALERT}}$ pin of a GD30TS302T on the bus is active, the chip responds to the SMBus Alert command and returns its slave address. If the alert state is activated by result higher than the High Limit Register, the eighth bit of the slave address byte (LSB) will be set to 1; If the alert state is activated by result below the Low Limit Register, the eighth bit of the slave address byte (LSB) is set to 0.

If more than one GD30TS302T on the bus responds to a SMBus Alert command at the same time, the bus returns the smallest two wires address. Then the $\overline{\text{ALERT}}$ pin of this GD30TS302T will be cleared.

The above function is detailed in [Figure 14](#).

6.2.5 General Call Reset

The GD30TS302T respond to the two-wire general call address 00h. The device acknowledges the general call address and responds to commands in the second byte. If the second byte is 06h, the GD30TS302T reset the internal registers to the power-up reset values, and aborts the current temperature conversion. If the second byte is other value, the GD30TS302T will not respond.

6.2.6 High-Speed Mode

For the two-wire bus to operate at frequencies above 400kHz, the master device must issue a high-speed mode (Hs-mode) master code (0000 1xxx) as the first byte after a START condition to switch the bus to high-speed operation. The GD30TS302T does not acknowledge this byte, but switches the input filters on SDA and SCL and the output filter on SDA to operate in Hs-mode, allowing transfers at up to 2.5MHz. After the Hs-mode master code has been issued, the master transmits a two-wire slave address to initiate a data transfer operation.

The bus continues to operate in Hs-mode until a STOP condition occurs on the bus. Upon receiving the STOP condition, the GD30TS302T switches the input and output filters back to fast mode operation.

6.2.7 Time-Out Function

GD30TS302T has the ability to detect serial bus timeouts. This function can be activated by writing the TO bit in the Consecutive Alert Register (22h) to 1. If the SDA and SCL remain low for 30ms (typical) between the START and STOP signals, the GD30TS302T will reset their serial interfaces, release the bus and wait for the START signal. To avoid activating the timeout function, the SCL operating frequency should be greater than 1kHz.

6.3 Register Descriptions

Table 5. GD30TS302T Register List

| POINTER ADDRESS | TYPE | POR | BIT DESCRIPTIONS | | | | | | | | REGISTER DESCRIPTIONS |
|-----------------|------|-----|------------------|--------|-------|-------|-------|-------|-------|-------|--|
| | | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
| 00 | R | 00h | LT11 | LT10 | LT9 | LT8 | LT7 | LT6 | LT5 | LT4 | Local Temperature Register (High Byte) |
| 01 | R | 00h | RT11 | RT10 | RT9 | RT8 | RT7 | RT6 | RT5 | RT4 | Remote Temperature 1 Register (High Byte) |
| 02 | R | 00h | BUSY | 0 | 0 | HIGH | LOW | OPEN | THERM | 0 | Status Register |
| 03/09 | R/W | 00h | MASK | SD | AL/TH | 0 | 0 | RANGE | 0 | 0 | Configuration Register 1 |
| 04/0A | R/W | 06h | 0 | 0 | 0 | 0 | R3 | R2 | R1 | R0 | Conversion rate Register |
| 05/0B | R/W | 55h | LTH11 | LTH10 | LTH9 | LTH8 | LTH7 | LTH6 | LTH5 | LTH4 | Local Temperature High Limit Register (High Byte) |
| 06/0C | R/W | 00h | LTL11 | LTL10 | LTL9 | LTL8 | LTL7 | LTL6 | LTL5 | LTL4 | Local Temperature Low Limit Register (High Byte) |
| 07/0D | R/W | 55h | RTH11 | RTH10 | RTH9 | RTH8 | RTH7 | RTH6 | RTH5 | RTH4 | Remote Temperature 1 High Limit Register (High Byte) |
| 08/0E | R/W | 00h | RTL11 | RTL10 | RTL9 | RTL8 | RTL7 | RTL6 | RTL5 | RTL4 | Remote Temperature 1 Low Limit Register (High Byte) |
| 0F | W | 00h | X | X | X | X | X | X | X | X | One-shot Register |
| 10 | R | 00h | RT3 | RT2 | RT1 | RT0 | 0 | 0 | 0 | 0 | Remote Temperature 1 Register (Low Byte) |
| 11 | R/W | 00h | X | X | X | X | X | X | X | X | User-defined |
| 12 | R/W | 00h | X | X | X | X | X | X | X | X | User-defined |
| 13 | R/W | 00h | RTH3 | RTH2 | RTH1 | RTH0 | 0 | 0 | 0 | 0 | Remote Temperature 1 High Limit Register (Low Byte) |
| 14 | R/W | 00h | RTL3 | RTL2 | RTL1 | RTL0 | 0 | 0 | 0 | 0 | Remote Temperature 1 Low Limit Register (Low Byte) |
| 15 | R/W | 55h | RTH11 | RTH10 | RTH9 | RTH8 | RTH7 | RTH6 | RTH5 | RTH4 | Remote Temperature 2 High Limit Register (High Byte) |
| 16 | R/W | 00h | RTL11 | RTL10 | RTL9 | RTL8 | RTL7 | RTL6 | RTL5 | RTL4 | Remote Temperature 2 Low Limit Register (High Byte) |
| 17 | R/W | 00h | RTH3 | RTH2 | RTH1 | RTH0 | 0 | 0 | 0 | 0 | Remote Temperature 2 High Limit Register (Low Byte) |
| 18 | R/W | 00h | RTL3 | RTL2 | RTL1 | RTL0 | 0 | 0 | 0 | 0 | Remote Temperature 2 Low Limit Register (Low Byte) |
| 19 | R/W | 55h | RTHL11 | RTHL10 | RTHL9 | RTHL8 | RTHL7 | RTHL6 | RTHL5 | RTHL4 | Remote 1 THERM Limit Register |
| 1A | R/W | 55h | RTHL11 | RTHL10 | RTHL9 | RTHL8 | RTHL7 | RTHL6 | RTHL5 | RTHL4 | Remote 2 THERM Limit Register |

| POINTER ADDRESS | TYPE | POR | BIT DESCRIPTIONS | | | | | | | | REGISTER DESCRIPTIONS |
|-----------------|------|-----|------------------|--------|-------|-------|-------|---------|---------|--------|----------------------------|
| | | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
| 1B | R | 00h | 0 | 0 | 0 | 0 | 0 | R2OPEN | R1OPEN | 0 | Open Status Register |
| 1F | R | 00h | 0 | 0 | 0 | 0 | 0 | R2MASK | R1MASK | LMASK | Channel Mask Register |
| 20 | R/W | 55h | LTHL11 | LTHL10 | LTHL9 | LTHL8 | LTHL7 | LTHL6 | LTHL5 | LTHL4 | Local THERM Limit Register |
| 21 | R/W | 0Ah | TH11 | TH10 | TH9 | TH8 | TH7 | TH6 | TH5 | TH4 | THERM Hysteresis Register |
| 22 | R/W | 70h | TO | CTH2 | CTH1 | CTH0 | CALT2 | CALT1 | CALT0 | 0 | Consecutive Alert Register |
| 23 | R | 00h | RT11 | RT10 | RT9 | RT8 | RT7 | RT6 | RT5 | RT4 | Remote Temperature 2 |
| 24 | R | 00h | RT3 | RT2 | RT1 | RT0 | 0 | 0 | 0 | 0 | Remote Temperature 2 |
| 25 | R/W | 08h | 0 | 0 | 0 | 0 | BC3 | BC2 | BC1 | BC0 | Remote Channel 1 |
| 26 | R/W | 08h | 0 | 0 | 0 | 0 | BC3 | BC2 | BC1 | BC0 | Remote Channel 2 |
| 27 | R/W | 00h | NC7 | NC6 | NC5 | NC4 | NC3 | NC2 | NC1 | NC0 | Remote Channel 1 |
| 28 | R/W | 00h | NC7 | NC6 | NC5 | NC4 | NC3 | NC2 | NC1 | NC0 | Remote Channel 2 |
| 29 | R | 00h | LT3 | LT2 | LT1 | LT0 | 0 | 0 | 0 | 0 | Local Temperature |
| 35 | R | 00h | 0 | 0 | 0 | 0 | 0 | R2HIGH | R1HIGH | LHIGH | High Limit Status Register |
| 36 | R | 00h | 0 | 0 | 0 | 0 | 0 | R2LOW | R1LOW | LLOW | Low Limit Status Register |
| 37 | R | 00h | 0 | 0 | 0 | 0 | 0 | R2THERM | R1THERM | LTHERM | THERM Status Register |
| 40 | R/W | 00h | 0 | 0 | 0 | 0 | 0 | 0 | FIL1 | FIL0 | Filter Control Register |
| 41 | R/W | 07h | 0 | 0 | 0 | 0 | 0 | REN2 | REN1 | LEN | Configuration Register 2 |
| FD | R | 21h | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | Device ID Register |
| FE | R | 5Dh | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | Manufacturer ID Register |
| FF | R | 03h | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | Revision Register |

6.3.1 Status Register

6.3.1.1 BUSY bit (POR=0)

BUSY=1: The internal ADC is converting temperature.

BUSY=0: The internal ADC is not converting temperature.

6.3.1.2 HIGH/LOW bit (POR=0)

The above bits are controlled by the corresponding bits in the High Limit Status Register (35h) or the Low Limit Status Register (36h) and satisfies the following conditions: HIGH = LHIGH **OR** R1HIGH **OR** R2HIGH; LOW = LLOW **OR** R1LOW **OR** R2LOW, where the LHIGH/R1HIGH/R2HIGH bits are controlled by the $\overline{AL/TH}$ bit in Configuration Register 1 Register, and the LLOW/R1LOW/R2LOW bits are only valid when $\overline{AL/TH} = 0$.

When $\overline{AL/TH} = 1$ in Configuration Register 1, the chip is in THERM2 Mode, and the LHIGH/R1HIGH/R2HIGH bits act as follows:

LHIGH/R1HIGH/R2HIGH=1: The local/remote channel result is higher than the value of the Local/Remote High Limit Register, and remains higher than the value of the Local/Remote High Limit Register minus the THERM Hysteresis Register of the corresponding channel.

LHIGH/R1HIGH/R2HIGH=0: The local/remote channel result is lower than the value of the Local/Remote High Limit Register minus the THERM Hysteresis Register of the corresponding channel.

When $\overline{AL/TH} = 0$ in Configuration Register 1, the chip is in ALERT Mode, and the LHIGH/R1HIGH/R2HIGH /LLOW/R1LOW/R2LOW bits act as follows:

LHIGH/R1HIGH/R2HIGH=1: The temperature result of the local/remote channel is higher than the value of the Local/Remote High Limit Register of the corresponding channel since the latest reset of above bits;

LHIGH/R1HIGH/R2HIGH=0: Reads the High Limit Status Register when the local/remote channel result is lower than the value of the Local/Remote High Limit Register of the corresponding channel; or the chip successfully corresponds to the SMBus alert command; or the chip successfully corresponds to General Call Reset.

LLOW/R1LOW/R2LOW=1: The temperature result of the Local/Remote channel is lower than the value of the Local/Remote Low Limit Register of the corresponding channel since the latest reset of above bits;

LLOW/R1LOW/R2LOW=0: Reads the Low Limit Status Register when the local/remote channel result is higher than the value of the Local/Remote Low Limit Register of the corresponding channel; or the chip successfully corresponds to the SMBus alert command; or the chip successfully corresponds to General Call Reset.

6.3.1.3 Open bit (POR=0)

GD30TS302T detects the OPEN status of the remote channel only when the remote channel is opened.

OPEN=1: Since the latest reset of OPEN bit, the remote BJT of any remote channel is open, and the bit in the Open Status Register (1Bh) is set to 1; OPEN = R1OPEN **OR** R2OPEN.

OPEN=0: When remote BJTs of all remote channel are not open and reading the Open Status Register will set R1OPEN/R2OPEN to 0; OPEN = R1OPEN **OR** R2OPEN.

6.3.1.4 THERM bit (POR=0)

This bit is controlled by the LTHERM/R1THERM/R2THERM bits in the THERM Status Register (37h) and satisfies the THERM = LTHERM **OR** R1THERM **OR** R2THERM.

LTHERM/R1THERM/R2THERM=1: The local/remote channel result is higher than the value of the Local/Remote THERM Limit Register of the corresponding channel, and remains higher than the value of the Local/Remote THERM Limit Register minus the THERM Hysteresis Register of the corresponding channel.

LTHERM/R1THERM/R2THERM=0: The local/remote channel result is lower than the value of the Local/Remote THERM Limit Register minus the THERM Hysteresis Register of the corresponding channel.

6.3.2 Configuration Register

The Configuration Register 1 of the GD30TS302T controls the conversion mode of the chip. Any write to this register immediately terminates the current temperature conversion, after which the chip restarts a new conversion or enters into Shutdown Mode (SD=1) based on the value written to the register. Table 8 shows the functions of Configuration Register 1.

Table 6. Configuration Register 1 Description

| BIT | Field | Default | Description |
|--------|---------------------------|---------|---|
| D7 | MASK | 0 | 1= $\overline{\text{ALERT}}$ pin is masked 0= $\overline{\text{ALERT}}$ is activated (only effective when $\overline{\text{AL/TH}}=0$) |
| D6 | SD | 0 | 1=Chip enters into Shutdown Mode 0= Chip enters into Continuous Conversion Mode |
| D5 | $\overline{\text{AL/TH}}$ | 0 | 1=Chip enters into THERM2 Mode 0= Chip enters into ALERT Mode |
| D2 | RANGE | 0 | 1= Chip enters into Extended Mode 0= Chip enters into Standard Mode |
| Others | Reserved | 0 | / |

The Configuration Register 2 of the GD30TS302T controls the enabling of the temperature measurement channel of the chip. Any write to this register immediately terminates the current temperature conversion, after which the chip restarts a new conversion or enters shutdown mode (LEN=REN1=REN2=0) based on the value written to

the register.

$$\eta_{\text{eff}} = \frac{1.008 \times 2150}{2150 + N}, N = \frac{1.008 \times 2150}{\eta_{\text{eff}}} - 2150$$

(1)

Table 9 shows the functions of Configuration Register 2.

Table 7. Configuration Register 2 Description

| BIT | Field | Default | Description |
|--------|----------|---------|---|
| D2 | REN2 | 1 | 1=Remote channel 2 is enabled 0=Remote channel 2 is shutdown |
| D1 | REN1 | 1 | 1=Remote channel 1 is enabled 0=Remote channel 1 is shutdown |
| D0 | LEN | 1 | 1=Local channel is enabled 0=Local channel is shutdown |
| Others | Reserved | 0 | / |

6.3.3 β Compensation Register

GD30TS302T can automatically detect the β value of the transistor-connected PNP and compensate for different β values, see [β Detection and Compensation](#) for details. The range of automatic compensation for β values is $0.09 < \beta < 21.36$. [Table 8](#) shows the register configuration for β compensation.

If the remote BJT is diode-connected, it is recommended to use the BJT with $\beta > 50$ and configure the β Compensation Register to 0111.

Table 8. β Compensation Register Description

| BCx3 ~ BCx0 | β Range Description |
|-------------|---|
| 1000 | Automatic: $0.09 < \beta < 0.20$ |
| 1001 | Automatic: $0.18 < \beta < 0.26$ |
| 1010 | Automatic: $0.24 < \beta < 0.38$ |
| 1011 | Automatic: $0.35 < \beta < 0.72$ |
| 1100 | Automatic: $0.64 < \beta < 1.68$ |
| 1101 | Automatic: $1.47 < \beta < 10.03$ |
| 1110 | Automatic: $6.83 < \beta < 61.90$ |
| 1111 | Automatic: $\beta > 21.36$ |
| 1111 | Automatic detect the diode-connected BJT |
| 0000 | Manual: $0.09 < \beta < 0.20$ |
| 0001 | Manual: $0.18 < \beta < 0.26$ |
| 0010 | Manual: $0.24 < \beta < 0.38$ |
| 0011 | Manual: $0.35 < \beta < 0.72$ |
| 0100 | Manual: $0.64 < \beta < 1.68$ |
| 0101 | Manual: $1.47 < \beta < 10.03$ |
| 0110 | Manual: $6.83 < \beta < 61.90$ |
| 0111 | Manually turn off β compensation function |

6.3.4 η -factor Correction Register

GD30TS302T supports remote BJT with different η factors. In the actual using process, the η -factor Correction Register should be correctly configured to avoid unnecessary temperature measurement errors.

$$\eta_{\text{eff}} = \frac{1.008 \times 2150}{2150 + N}, N = \frac{1.008 \times 2150}{\eta_{\text{eff}}} - 2150$$

The configuration of the η -factor Correction Register is shown in

(1)

Table 9; where η_{eff} is the value of the η factor of the remote BJT, N is the value of the η -factor Correction Register (negative value is expressed in the form of binary complement) and the trimming range is -128 ~ +127. When the default value of the η -factor is $\eta_{\text{default}} = 1.008$, the correspondence is shown in the following formula:

$$\eta_{\text{eff}} = \frac{1.008 \times 2150}{2150 + N}, N = \frac{1.008 \times 2150}{\eta_{\text{eff}}} - 2150 \quad (1)$$

Table 9. η -factor Correction Register Description

| N | | | η |
|-----------|-----|---------|-----------------|
| Binary | HEX | Decimal | |
| 0111 1111 | 7F | 127 | 0.951779 |
| 0000 1010 | 0A | 10 | 1.003333 |
| 0000 1000 | 08 | 8 | 1.004263 |
| 0000 0110 | 06 | 6 | 1.005195 |
| 0000 0100 | 04 | 4 | 1.006128 |
| 0000 0010 | 02 | 2 | 1.007063 |
| 0000 0001 | 01 | 1 | 1.007531 |
| 0000 0000 | 00 | 0 | 1.008 (default) |
| 1111 1111 | FF | -1 | 1.008469 |
| 1111 1110 | FE | -2 | 1.008939 |
| 1111 1100 | FC | -4 | 1.009879 |
| 1111 1010 | FA | -6 | 1.010821 |
| 1111 1000 | F8 | -8 | 1.011765 |
| 1111 0110 | F6 | -10 | 1.012710 |
| 1000 0000 | 80 | -128 | 1.071810 |

6.3.5 Conversion Rate Register

The Conversion Rate Register controls the time of the Idle State between two conversions, but not the conversion time itself. Table 10 shows the configuration of the Conversion Rate Register. In particular, if the conversion time is longer than the time shown in the table, there is no more idle time between two conversions.

Table 10. Conversion Rate Register Description

| R3 | R2 | R1 | R0 | CONV per Sec | Average Current (TYP) |
|--------|----|----|----|--------------|-----------------------|
| 0 | 0 | 0 | 0 | 0.0625 | 16μA |
| 0 | 0 | 0 | 1 | 0.125 | 18μA |
| 0 | 0 | 1 | 0 | 0.25 | 20μA |
| 0 | 0 | 1 | 1 | 0.5 | 25μA |
| 0 | 1 | 0 | 0 | 1 | 45μA |
| 0 | 1 | 0 | 1 | 2 | 60μA |
| 0 | 1 | 1 | 0 | 4(default) | 90μA |
| 0 | 1 | 1 | 1 | 8 | 140μA |
| 1 | 0 | 0 | 0 | 16 | 250μA |
| 1 | 0 | 0 | 1 | 32 | 315μA |
| 1 | 0 | 1 | 0 | 64 | 315μA |
| Others | | | | 1 | 45μA |

6.3.6 Consecutive Alert Register

This register controls the times of over-temperature required for GD30TS302T to activate the $\overline{\text{THERM}}$ and $\overline{\text{ALERT/THERM2}}$ pin. This function helps to avoid jitter around the alert limit, which may cause the chip to repeatedly activate the alert pin. Table 11 shows the configuration of this register.

Table 11. Consecutive Alert Register Description

| CALT2/CTH2 | CALT1/CTH1 | CALT0/CTH0 | Times |
|------------|------------|------------|----------------------------|
| 0 | 0 | 0 | 1 (default for CALT2:0) |
| 0 | 0 | 1 | 2 |
| 0 | 1 | 1 | 3 |
| 1 | 1 | 1 | 4 (default for CTH2:0) |

6.3.7 Filter Control Register

Table 12. Filter Control Register Description

| FIL1 | FIL0 | CALT0/CTH0 |
|------|------|-------------------|
| 0 | 0 | Disabled(default) |
| 0 | 0 | Level 1 |
| 0 | 1 | Level 1 |
| 1 | 1 | Level 2 |

7 Application Information

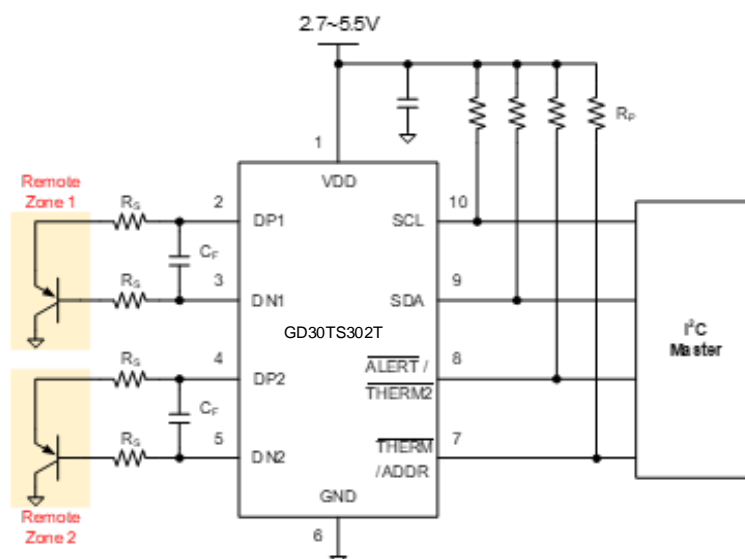


Figure 15. Typical Application Schematics

GD30TS302T provides β value detection and automatic compensation function to obtain accurate remote temperature measurement results when using transistor-connected PNP. The range of compensation for transistor-connected PNP is $0.09 < \beta < 21.36$. When using a diode-connected PNP / NPN, GD30TS302T automatically detects this diode-connection and shuts down the internal β compensation circuitry, regardless of the β Compensation Register configuration.

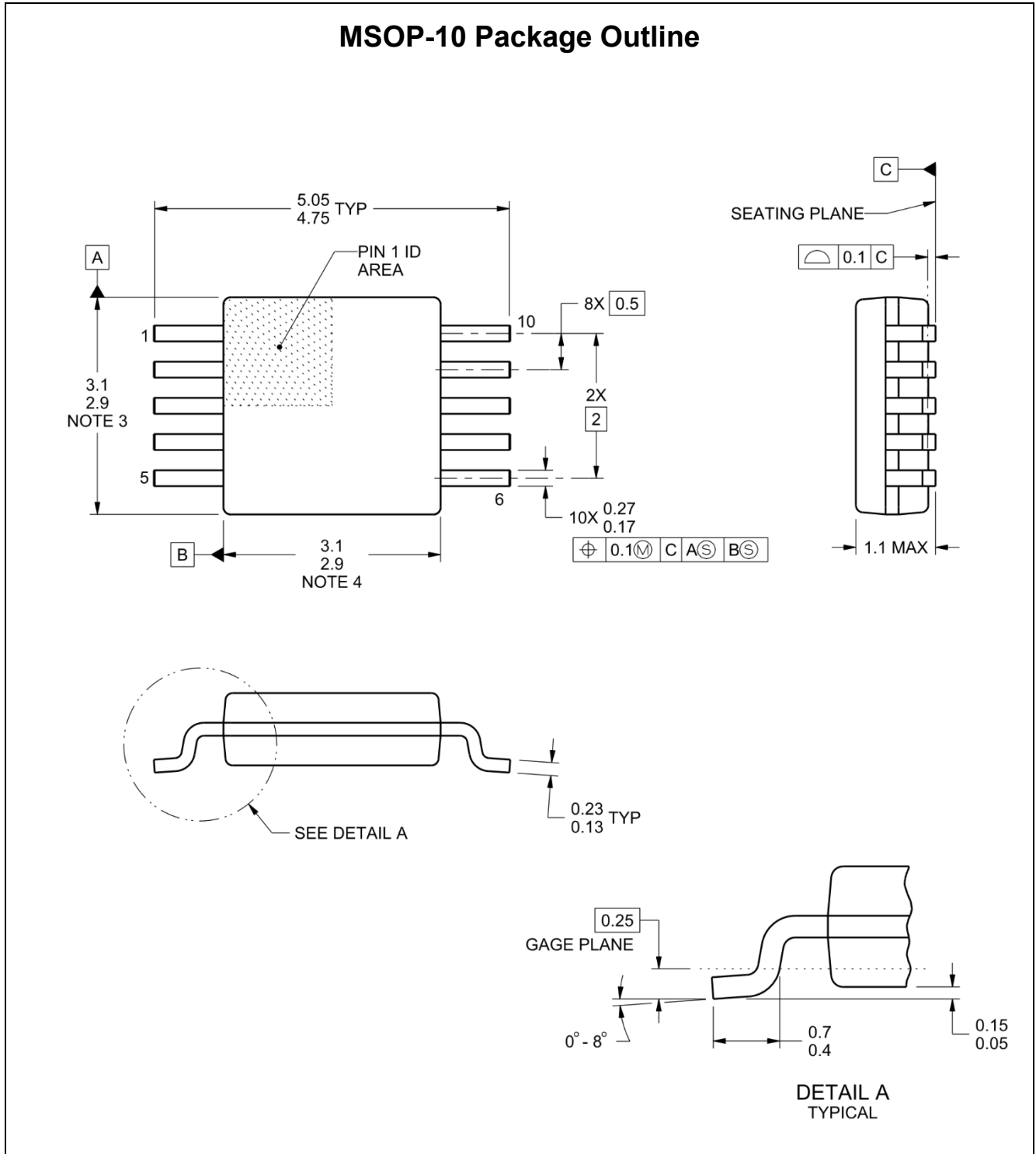
Therefore, if it is necessary to use a diode-connected PNP / NPN for remote temperature measurement, or to manually configure the β compensation register to 0111, the BJT used should be correctly selected, and the selection criteria are as follows:

- $V_{BE} > 0.25V$ at the maximum measured temperature and bias current of $7.5\mu A$;
- $V_{BE} < 0.95V$ at the lowest measured temperature and bias current of $120\mu A$;
- Base resistance $< 100\Omega$;
- The range of β value variation is as small as possible (50~150);

Based on the above criteria, the recommended remote temperature BJT is MMBT3904 (NPN) or MMBT3906 (PNP).

8 Package Information

8.1 Outline Dimensions



NOTES: (continued)

1. All dimensions are in millimeters.
2. Package dimensions does not include mold flash, protrusions, or gate burrs.

9 Ordering Information

| Ordering Code | Package Type | ECO Plan | Packing Type | MOQ | OP Temp(°C) |
|--------------------|--------------|----------|--------------|------|-----------------|
| GD30TS302TAMTR-I0A | MSOP-10 | Green | Tape & Reel | 3000 | -40°C to +125°C |
| GD30TS302TAMTR-I0B | MSOP-10 | Green | Tape & Reel | 3000 | -40°C to +125°C |
| GD30TS302TAMTR-I0C | MSOP-10 | Green | Tape & Reel | 3000 | -40°C to +125°C |
| GD30TS302TAETR-I0A | DFN-10 | Green | Tape & Reel | 3000 | -40°C to +125°C |

10 Revision History

| REVISION NUMBER | DESCRIPTION | DATE |
|-----------------|------------------------------------|------|
| 1.0 | Initial release and device details | 2024 |

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